## Somatic growth dilution

Toxin predator-prey model under stoichiometric constraints

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# Outline

- Mercury as a toxin and bioaccumulation
- Model formulation: Ecotoxicology and Ecological Stoichiometry
- Model parameterization
- Basic model analysis
- Numerical simulations and bifurcation analysis



### Basic ecotoxicology model Wang et al. 1996



uptake from water



uptake from consuming prey



loss due to efflux & growth

- v predator body burden
- a<sub>2</sub> toxin uptake rate
- T environmental toxin conc.
- *u* prey body burden

- $\xi$  toxin assimilation efficiency
- f predator's ingestion rate
- $\sigma_2$  toxin efflux rate
- g predator's growth rate

## Somatic growth dilution

Predator experiences a greater than proportional gain in biomass relative to MeHg under high growth conditions.



Karimi et al. 2007 showed that *Daphnia* grown on high quality food had 3.5 times higher growth rates and lower MeHg body burden



#### Ecological Stoichiometry and Ecotoxicology

Can Ecological Stoichiometry help improve testing protocols for assessing risk of exposures?



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# Goal: How does MeHg bioaccumulate under stoichiometric constraints?



 $\mathsf{Algae}^*$ 



Daphnia

- Model the trophic transfer of MeHg in aquatic food chain
- Investigate how varying food quality affects toxin bioaccumulation
- Explore dynamics of Somatic Growth Dilution (SGD)

\*Image credit: http://protist.i.hosei.ac.jp/pdb/images/chlorophyta/scenedesmus

We start with a Toxin-mediated predator-prey model: Huang et al. 2014



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## Expand under the Ecological Stoichiometry Framework

#### Stoichiometric compositions

- Composition of algae depends on light and nutrient availability
- Varying food quality can influence how MeHg bioaccumulates •  $Q = \frac{P - \theta y}{x}$
- Prey growth b(u, x) and predator conversion efficiency e(v) depend on nutrient availability

$$b(u,x) \rightarrow b(u,x,y)$$
  $e(v) \rightarrow e(v,x,y)$ 

## Prey growth

$$b(u, x, y) = \alpha_1 \max\{0, 1 - \alpha_2 u\} \left(1 - \frac{x}{\min\left\{K, \frac{P - \theta_y}{q}\right\}}\right)$$

- x prey density
- y predator density
- *u* prey body burden
- $\alpha_1$  maximum prey growth rate
- $\alpha_2$  toxin affect on prey growth

- K producer carrying capacity
- P total phosphorus in the system
- q producer minimal P:C
- $\theta$  grazer's constant P:C

Predator conversion efficiency

$$e(v, x, y) = \min\left\{eta_1, rac{Q}{ heta}
ight\} \max\{0, 1 - eta_2 v\}$$

- x prey density
- y predator density
- v predator body burden
- $\beta_1$  predator C growth efficiency

- $\beta_2$  toxin affect on predator growth
- P total phosphorus in the system
- $\theta$  grazer's constant P:C
- $Q = \frac{P \theta y}{x}$  producer varying P:C

#### The stoichiometric toxin-mediated predator-prey system takes the final form:

$$\underbrace{\frac{dx}{dt}}_{Change in prey} = \underbrace{\alpha_1 \max\{0, 1 - \alpha_2 u\}}_{gain from} \left(1 - \frac{x}{\min\left\{K, \frac{P - \theta_Y}{q}\right\}}\right) x - \underbrace{f(x)y}_{loss from}$$

$$\underbrace{\frac{dy}{dt}}_{Change in} = \underbrace{\min\left\{\beta_1, \frac{Q}{\theta}\right\}}_{gain from} \max\{0, 1 - \beta_2 v\} f(x)y - \underbrace{\frac{d_2(v)y}{loss from}}_{death}$$

$$\underbrace{\frac{du}{dt}}_{Change in toxin} = \underbrace{a_1 T}_{uptake} - \underbrace{\sigma_1 u}_{efflux} - \alpha_1 \max\{0, 1 - \alpha_2 u\} \left(1 - \frac{x}{\min\left\{K, \frac{P - \theta_Y}{q}\right\}}\right) u$$

$$\underbrace{\frac{dv}{dt}}_{Change in toxin} = \underbrace{a_2 T}_{uptake} + \underbrace{\xi f(x)u}_{uptake from} - \underbrace{\sigma_2 v}_{efflux} - \underbrace{\min\left\{\beta_1, \frac{Q}{\theta}\right\}}_{loss due to} \max\{0, 1 - \beta_2 v\} f(x)v$$

$$\underbrace{\frac{dv}{dt}}_{loss due to} = \underbrace{a_2 T}_{uptake} + \underbrace{\xi f(x)u}_{uptake from} - \underbrace{\sigma_2 v}_{efflux} - \underbrace{\min\left\{\beta_1, \frac{Q}{\theta}\right\}}_{loss due to} \max\{0, 1 - \beta_2 v\} f(x)v$$

#### Model parameterization

$\alpha_1$	Algae maximal growth rate	1.2/day	
$\alpha_2$	Toxin effect on algal reproduction	0.0051 mg C/ $\mu$ g T	*
Κ	Algae C carrying capacity	0-3 mg C/L	
$\beta_1$	Daphnia C growth efficiency	0.8 (unitless)	
$\beta_2$	Toxin effect on Daphnia reproduction	10.13 mg C/ $\mu$ g T	*
$\theta$	Daphnia constant P:C	0.03 mg P/mg C	
q	Algae minimal P:C	0.0038 mg P/mg C	
$h_2$	Toxin Coefficient for Daphnia mortality	64 mg C $/\mu$ g T $/$ day	*
1	Toxin Exponent for Daphnia mortality	1.17 (unitless)	*
$m_2$	Daphnia natural mortality	0.25/day	
С	Daphnia max ingestion rate	0.81/day	
а	Daphnia ingestion half saturation constant	0.25 mgC/L	
$a_1$	Algae uptake coefficient	0.012 L/mg C/day	
$a_2$	Daphnia uptake coefficient	0.011 L/mg C/day	
$\sigma_1$	Algae toxin efflux rate	0.048/day	
$\sigma_2$	Daphnia toxin efflux rate	0.04/day	
ξ	Daphnia toxin assimilation efficiency	0.97 (unitless)	
Т	Total Toxin	$\mu$ g MeHg / L	
Р	Total phosphorus	mg 0.01-0.08 mg P/ L $$	

 $\alpha_2$ : toxin effect on algal reproduction

$$b(u, x, y) = \alpha_1 \max\{0, 1 - \frac{\alpha_2 u}{2}u\} \left(1 - \frac{x}{\min\left\{K, \frac{P - \theta_y}{q}\right\}}\right)$$

To estimate  $\alpha_2$  we use

$$\frac{1}{\alpha_2} = \frac{a_1}{\sigma_1} T_0$$

where

- *a*<sub>1</sub> algal MeHg uptake rate
- $\sigma_1$  algal MeHg efflux rate
- $T_0$  MeHg conc. that inhibits growth 100%
- $\alpha_2$  MeHg affect on algal growth

 $\beta_2$ : toxin effect on *Daphnia* reproduction  $e(v, x, y) = \min \left\{ \beta_1, \frac{Q}{\theta} \right\} \max\{0, 1 - \beta_2 v\}$ 

We fit data presented by *Biesinger et al. 1982* on the average number of neonates produced by *Daphnia magna* throughout 21 days of exposure to MeHg



## $d_2(v)$ : Daphnia mortality

$$d_2(v) = \frac{h_2}{v'} + m_2$$

We fit data presented by *Tsui et al. 2006* on the percent survival of juvenile *Daphnia magna* after 24 hours of exposure to treatments of  $1.5-7\mu g$  Hg / L.



Nondimensionalization

$$\begin{split} \widetilde{u} &= \alpha_2 u, \qquad \widetilde{m_2} = \frac{m_2}{\alpha_1}, \qquad \widetilde{\beta_1} = \frac{c\beta_1}{\alpha_1}, \qquad \widetilde{\beta_2} = \frac{\xi c\sigma_1\beta_2}{\alpha_2}, \qquad \gamma = \frac{a_2\beta_2}{\alpha_2a_1}, \\ \widetilde{v} &= \beta_2 v, \qquad \epsilon = \alpha_1\sigma_1, \qquad \widetilde{t} = \alpha_1t, \qquad \widetilde{\sigma_2} = \sigma_2\sigma_1, \qquad \widetilde{T} = \alpha_2a_1\sigma_1T, \\ \widetilde{y} &= \frac{c}{\alpha_1}y, \qquad \widetilde{h_1} = \frac{h_1}{\alpha_1\alpha_2}, \qquad \widetilde{h_2} = \frac{h_2}{\beta_2\alpha_1}, \qquad \widetilde{\theta} = \frac{\alpha_1\theta}{c}, \qquad \widetilde{Q} = \frac{P - \widetilde{\theta}\widetilde{y}}{x}. \end{split}$$

Dropping the tildes, the system can be written:

$$\frac{dx}{dt} = \max\{0, 1-u\} \left(1 - \frac{x}{\min\left\{K, \frac{P - \theta y}{q}\right\}}\right) x - \frac{xy}{a+x}$$
$$\frac{dy}{dt} = \min\left\{\beta_1, \frac{Q}{\theta}\right\} \max\{0, 1-v\} \frac{xy}{a+x} - (h_2v + m_2)y$$
$$\epsilon \frac{du}{dt} = T - \sigma_2^2 u - \epsilon \max\{0, 1-u\} \left(1 - \frac{x}{\min\left\{K, \frac{P - \theta y}{q}\right\}}\right) u$$
$$\epsilon \frac{dv}{dt} = \gamma T - \sigma_2 v + \left[\beta_2 u - \epsilon \min\left\{\beta_1, \frac{Q}{\theta}\right\} \max\{0, 1-v\}v\right] \frac{x}{a+x}$$

Quasi-steady state assumption:  $\epsilon 
ightarrow 0$ 

$$u = \frac{T}{\sigma_1^2}, \qquad v = \frac{T}{\sigma_2} \left( \gamma + \frac{\beta_2}{\sigma_1^2} \frac{x}{a+x} \right)$$

The reduced system becomes:

$$\frac{dx}{dt} = \max\left\{0, 1 - \frac{T}{\sigma_1^2}\right\} \left(1 - \frac{x}{\min\left\{K, \frac{P - \theta_Y}{q}\right\}}\right) x - \frac{xy}{a + x}$$
$$\frac{dy}{dt} = \min\left\{\beta_1, \frac{Q}{\theta}\right\} \max\left\{0, 1 - \frac{T}{\sigma_2}\left(\gamma + \frac{\beta_2}{\sigma_1^2}\frac{x}{a + x}\right)\right\} \frac{xy}{a + x} - \left(\frac{h_2 T}{\sigma_2}\left(\gamma + \frac{\beta_2}{\sigma_1^2}\frac{x}{a + x}\right) + m_2\right) y$$

which can be written as:

$$\frac{dx}{dt} = xF(x, y)$$
$$\frac{dy}{dt} = yG(x, y)$$

#### Boundedness and positive invariance

Solutions to reduced system with initial conditions in the set

$$\Omega = \left\{ (x, y) : 0 \le x \le \mathbf{k} = \min\left\{ K, \frac{P}{q} \right\}, 0 \le y, qx + \theta y < P \right\}$$

will remain there for all forward time.

#### Boundary equilibria

 $E_0 = (0,0)$  is saddle point. The stability of  $E_1 = (\mathbf{k}, 0)$  depends on the sign of  $G(\mathbf{k}, 0)$ .  $E_1$  is locally asymptotically stable if  $G(\mathbf{k}, 0) < 0$  and  $E_1$  is saddle point if  $G(\mathbf{k}, 0) > 0$ .

## Model simulations



**Bifurcation dynamics** 



## **Bifurcation dynamics**



## Conclusion

- Developed a predator-prey model of MeHg accumulation under vary nutrient constraints
- Parameterized the model for algae-Daphnia system
- Model predicts that rapid growth from high-quality food can reduce the accumulation and trophic transfer of MeHg in predators
- Ecological Stoichiometry can help improve testing protocols for assessing risk of exposures

## Thank you









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